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TRANSLATION OF INTERNATIONAL APPLICATION NO. PCT/EP99/05885

[0001] DIFFERENTIAL FOR A MOTOR VEHICLE

[0002] AREA OF APPLICATION OF THE INVENTION

[0003] The present invention concerns a transfer case or differential with a bevel-pinion shaft which is supported in a drive housing by two spaced and axially pretensioned roller bearings and which drives via a bevel pinion and ring gear a differential unit mounted in the drive housing, axle shafts being supported in the differential unit which are operationally connected with each other via output and differential gears.

[0004] BACKGROUND

[0005] Such differential gear boxes permit the drive wheels of each axle shaft to roll in slip-free fashion at a different speed of rotation in travelling over a curved path. A bevel-pinion shaft or a drive shaft with a bevel gear drives a ring gear rotationally joined with the differential unit in the interior of which are mounted output and differential gears. While driving straight ahead, these differential gears in the differential unit are at rest so that both axle shafts turn at the same speed of rotation as the ring gear. Upon driving in a curved path, a difference occurs in the speed of rotation of the two axle shafts. In this case, the differential gears rotate and result in the fact that the increase in the speed of rotation of the one axle shaft compared to the speed of rotation of the ring gear is precisely as large as the decrease in the speed of rotation of the other axle shaft compared to the ring gear.

[0006] Such a generic differential gear box is described, for example, in the handbook "Roller Bearings -- Computation and Design" by W. Hampp, Springer-Verlag Berlin/Heidelberg/New York in Figure 88. The bevel pinion shaft is supported in this

case via two spaced conical-roller bearings pretensioned in the axial direction. The pretensioning occurs as a result of the conical-roller bearings being moved toward each other in the axial direction via a threaded connection.

[0007] Disadvantageous here is that fact that due to the pretensioning of the conical-roller bearings, sliding friction develops between the end walls of the conical rollers and the edge surface of the bearing rings, which leads to wear of the conical rollers and edge surfaces. This wear, in turn, is responsible for loss in pretensioning of the bearing, as a result of which there occurs an increase in tooth play between the bevel pinion and the ring gear, with its negative consequences.

[0008] **SUMMARY**

[0009] The present invention is therefore directed to developing an improved bearing arrangement for the bevel-pinion shaft of a differential.

[0010] According to the present invention, this problem is solved with the characterizing portion of Claim 1 through the fact that the roller bearings are designed as unilaterally loadable double-row tandem angular-contact ball bearings which face each other in an O-arrangement.

[0011] The advantages of the solution of the present invention compared to the classical solution with conical-roller bearings are the following:

[0012] Due to the substantially reduced frictional moment based on the lack of sliding friction in the bearing arrangement of the present invention, there necessarily also result reduced bearing temperatures and accordingly also a reduced oil-sump temperature. Thus, overall, better efficiency and a lower power loss of the bearing arrangement are attained. Upon installation of the bearing arrangement of the present invention in a motor vehicle, reduced fuel consumption is now possible as a result of the lower power loss. The approximately 40°C lower temperatures of the oil sump also make it possible

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that a lighter housing material, for example, a magnesium alloy can be employed for the differential housing which, in turn, makes itself felt in a saving of weight.

[0013] A further advantage is a reduced wear of the bearing, which amounts to only about 1/10 of the wear for the classical solution. This reduced wear accounts for the avoidance of axial shifting of the bevel-pinion shaft along with the known negative increase in tooth play between the bevel pinion on the bevel-pinion shaft and the ring gear connected with the differential unit.

[0014] Further advantageous refinements of the solution of the present invention are described in dependent claims 2-6. Thus, according to Claims 2 and 3, one provides that the races of a bearing exhibit respectively the same or a different diameter and the same or a different pressure angle.

[0015] According to a further feature relating to Claim 4, the bearing balls of both races of a bearing are guided in cages and have the same or a different diameter.

[0016] It is clear from Claim 5 that the first double-row tandem angular-contact ball bearing positioned next to the bevel pinion on the bevel-pinion shaft is larger than the accompanying second bearing. This appropriate refinement is undertaken because the greatest loads both in the radial as well as in the axial direction need to be accommodated in the immediate vicinity of the bevel pinion.

[0017] Finally, it is clear from Claim 6 that the inner ring of the second double-row tandem angular-contact ball bearing is supported in the axial direction against a deformable sleeve. After adjustment for the desired pretensioning, this sleeve provides for the fact that the adjustment screw is likewise put under pretensioning through the action of a counter force. Spontaneous loosening of this threaded screw is therefore not possible.

[0018] According to the second independent Claim 7, the problem of the present invention is also solved through the fact that the roller bearings are each designed as two

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unilaterally loadable single-unit angular-contact ball bearings in tandem arrangement, with the bearings facing each other in an O-arrangement.

[0019] The present invention is described in more detail on the basis of the following preferred embodiment.

[0020] **BRIEF DESCRIPTION OF THE DRAWINGS**

[0021] Figure 1 is a cross-section through a differential of a motor vehicle according to the prior art,

[0022] Figure 2 is a longitudinal cross-section through a bevel-pinion shaft with the bearing arrangement of the present invention.

[0023] **DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS**

[0024] The motor-vehicle differential shown in Figure 1 includes a housing 1 in which a differential unit 2 is supported via two conical-roller bearings 3. A bevel pinion 4 on a bevel-pinion shaft 5 drives a ring gear 6, which, in turn, sets the differential unit 2 in motion. The differential unit 2 is connected via differential gears 7 and output gears 8 with each of the axle shafts 9, which drive unshown wheels. The bevel-pinion shaft 5 is likewise held in housing 1 via two additional spaced-apart conical-roller bearings 10, which are moved toward each other in the axial direction by a threaded piece 11; i.e., put under pretensioning.

[0025] The inner rings 12 of conical-roller bearings 10 are provided with a radially outwardly directed edge 13 against which the end wall of conical rollers 14 run. Through the pretensioned conical-roller bearings 10, sliding friction develops between the end walls of conical rollers 14 and the inner surface of edge 13, which leads to wear through removal of material and has a negative effect on the final drive, i.e., such support of the bevel-pinion shaft 5 according to the state of the art involves a high frictional moment, high bearing and oil temperatures, as well as poor efficiency. In addition, the loss in

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pretensioning developing as a result of the wear of the conical rollers and edge surfaces leads to an increase in tooth play between bevel pinion 4 and ring gear 6.

[0026] The bevel-pinion shaft 5 of a differential shown in Figure 2 includes a stepped shank 15 on whose right-side end lies bevel pinion 4. In housing 1, the bevel-pinion shaft 5 is held by two spaced-apart tandem angular-contact ball bearings 16 and 17 which each include a one-piece bearing inner ring 18 and a one-piece bearing outer ring 19, with each ring having two shoulders 20 and 21. The bearing balls 22 and 23 are of the same size within bearings 16 and 17 and are guided in each case in bearing cages 24. One can further see from the figure that within a given bearing 16 and 17, the not more closely designated races of bearing balls 22 and 23 possess a different diameter. Since the greatest radial and axial stressing of bevel-pinion shaft 5 occurs in the area of bevel pinion 4, tandem angular-contact ball bearing 16 is substantially larger than tandem angular-contact ball bearing 17. As a result of the O-arrangement of the two tandem angular-contact ball bearings 16 and 17 with respect to each other, one ensures that one of bearings 16,17 can accommodate any force in an axial direction, i.e., axial shifting of the bevel-pinion shaft 5 is not possible. The pretensioning is produced in known fashion as a result of the fact that bevel pinion 4 is moved in the direction of housing 1, i.e., axially toward the left by screwing threaded piece 11 onto shank 15 of bevel-pinion shaft 5 so that both bearings 16,17 are put under pretensioning. A sleeve 25 is positioned between bearings 16 and 17 on trunk 15 of bevel-pinion shaft 5. This sleeve is supported, on the one hand, on inner ring 18 of bearing 17 and, on the other hand, on an undesignated step of shank 15. Upon tightening threaded piece 11, the bearing inner ring 18 of bearing 17 is first shifted toward the right so that a deformation force is exerted on sleeve 25, i.e., the latter becomes deformed. As a result of this deformation, however, a counter force is exerted by sleeve 25 on the inner ring 18 of bearing 17 so that threaded piece 11 is loaded with this counter force and can consequently not undergo spontaneous loosening from the threading of the shank 15 of bevel-pinion shaft 5.

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[0027] In contrast to the classical support of bevel-pinion shaft 5 with conical-roller bearings 10, only rolling friction is present, and even with relatively strong pretensioning, i.e., wear is very greatly reduced.

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Element Numbers

- 1 housing
- 2 differential unit
- 3 conical-roller bearing
- 4 bevel pinion
- 5 bevel-pinion shaft
- 6 ring gear
- 7 differential gear
- 8 output gear
- 9 axle shaft
- 10 conical-roller bearing
- 11 threaded piece
- 12 inner ring
- 13 edge
- 14 conical roller
- 15 shank
- 16 tandem angular-contact ball bearing
- 17 tandem angular-contact ball bearing
- 18 inner ring
- 19 outer ring
- 20 shoulder
- 21 shoulder
- 22 bearing ball
- 23 bearing ball
- 24 cage
- 25 sleeve

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